

# **REAL TIME OPERATING SYSTEM PROGRAMMING-I: $\mu$ C/OS-II and VxWorks**

## **Lesson-2: $\mu$ C/OS-II Features**

# 1. Developer

# Developed by Jean J. Labrosse

- Jean J. Labrosse designed it in 1992
- $\mu$ C/OS-II name derives from Micro-Controller Operating System
- Also known as MUCOS, UCOS, ..

## **2. Characteristics**

# Characteristics

- Preemptive RTOS
- Multitasking
- Deterministic
- Portable as ROM image
- Scalable
- Different Platforms support

# Characteristics

- Full source code availability

[www.micrium.com](http://www.micrium.com)

- Elegantly and very well documented in the book by its designer

# Basic Feature

- Scalable OS – only needed OS functions become part of the application codes
- Configuration file includes the user definitions for needed functions
- Multitasking preemptive scheduler
- Elegant code
- Is said to offer best high quality/performance ratio

# Basic Feature...

- Pre-certifiable software component for safety critical systems, including avionics system clockA DO-178B and EUROCAE ED-12B, medical FDA 510(k), and IEC 61058 standard for transportation and nuclear systems, respectively
- Source code has been certified by Department of Defense, USA for use in Avionics and in medical applications.



# Applications

- Automotive,
- avionics,
- consumer electronics,
- medical devices,
- military,
- aerospace,
- networking, and
- systems-on-a-chip.

# MUCOS real time kernel additional support

- $\mu$ C/BuildingBlocks [an embedded system building blocks (software components) for hardware peripherals, for example clock ( $\mu$ C/Clk) and LCD ( $\mu$ C/LCD)]
- $\mu$ C/FL (an embedded flash memory loader)
- $\mu$ C/FS (an embedded memory file system)
- $\mu$ C/GUI (an embedded GUI platform),
- $\mu$ C/Probe (a real time monitoring tool),

# MUCOS real time kernel additional support ...

- $\mu$ C/TCP-IP (an embedded TCP/IP stack),
- $\mu$ C/CAN (an embedded Controller Area Network bus)
- $\mu$ C/MOD (an embedded Modbus ) and
- $\mu$ C/USB device and  $\mu$ C/USB host (an embedded USB devices framework).

# Code Language

- ‘C’ and CPU Specific Codes in Assembly

# 3. Source Files

# Source Files

- Master Header file, which has the ‘#include’s and Processor dependent source files and ucos.ii.h and ucos.ii.c files
- os\_cfg.h — for Kernel building configuration file and
- os\_cpu.h — a header file for preprocessor definitions

# Source Files...

- `os_tick.c` — timer related codes file
- `os_cpu.c` — preprocessor C Codes
- `os_cpu_a.s12` — An example of assembly codes file for 68HC12
- `os_mem.c` for memory functions
- `os_sem.c`, `os_mbox.c` and `os_q.c` for semaphores, mailbox and queues

# 4. Naming Basics



# MUCOS Naming Basics

- OS or OS\_ prefix denotes that the function or variable is a MUCOS operating system function or variable
- For examples, OSTaskCreate () — a MUCOS function that creates a task,

# Macros

- OS\_NO\_ERR— a MUCOS macro that returns true in case no error is reported from a function
- OS\_MAX\_TASKS— user definable constant for specifying maximum number of tasks in user application

# **5. MUCOS Basic Functions**

# MUCOS Basic Functions

- System Level – OS initiate, start, system timer set, ISR enter and exit
- Task Service Functions – create, run, suspend, resume, ..
- Task delay
- Memory allocation, partitioning, ...

# MUCOS Basic Functions...

- IPCs – Semaphore, Queue and Mailbox
- Same Semaphore function usable as event flag, resource key and counting semaphore
- Mailbox one message pointer per mailbox
- Queue permit array of message-pointers

# Summary

## We learnt

- MUCOS characteristics, applications, basic features and functions

**End of Lesson 2 of Chapter 11**  
**on**  
 **$\mu$ C/OS-II Features**